

B2AGI

PHYSICAL AI RANKING 2027

The places, companies and people
taking intelligence into physical work.



What happens after the demonstration?

The task. The customer. The cost. The responsibility.



Chapter 02 · Concept artwork

390 entries. Seven lists.

20	Countries & Economies	50	Influence 50
20	Cities & Industrial Clusters	50	Ecosystem Builders
100	Current companies	50	Institutions
100	Next companies	Numerical ranks apply only to countries and clusters.	

Five analytical lenses

Intelligence	Physical	Capital	Trust	Beyond
Capability	Useful work	Financing	Operating responsibility	Future capacity

Intelligence and Beyond lead the geographic assessment.

Qualitative comparative assessment

Countries & Economies

01 United States

02 China

03 South Korea

04 Japan

05 Germany

Leading five of 20 · B2AGI qualitative assessment · October 2026

Cities & Industrial Clusters

01 Pearl River Delta Core — Shenzhen–Dongguan

02 San Francisco Bay Area

03 Yangtze River Delta Core — Shanghai–Hangzhou–Suzhou

04 Beijing Region

05 Seoul Capital Area

Leading five of 20 · Analytical regions have different boundaries.

200 companies. Two selections.

Read the product, task, operating stage and contribution.

Current 100

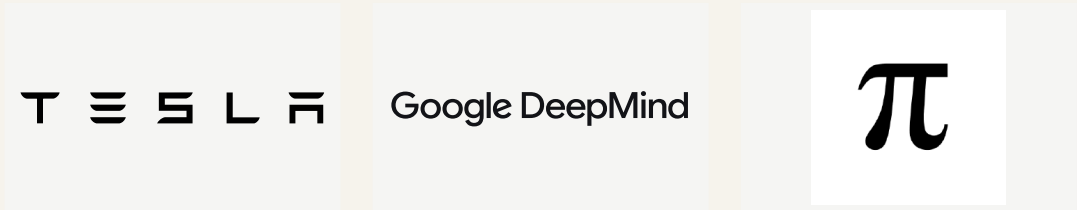


NVIDIA

Boston Dynamics

Unitree Robotics

Next 100



Tesla

Google DeepMind

Physical
Intelligence

Examples from the selections · Full lists in the appendix

Companies selected for their documented contributions to Physical AI

100 people. Different contributions.

Influence 50

Who advances
the technology?



Jensen Huang



Marc Raibert



Wang Xingxing

Ecosystem Builders 50

Who builds the conditions
for others to advance it?



Fei-Fei Li



Daniela Rus



Dennis Hong

Selection based on documented contribution

Editorial portrait illustrations

Institutions 50

The infrastructure behind the industry

MIT CSAIL

Human-robot interaction research

CMU Robotics Institute

Robotics research and education

KAIST

Shared humanoid research platforms

IFR

Robot statistics and definitions

NIST

Robotics measurement methods

Open Robotics / OSRF

Open robotics software infrastructure

Institutions selected by role and documented contribution

Examples from the selection · Full list and sources in the appendix

How to read an entry

Contribution

Rationale

Evidence scope

Sources

Related records

Start with what is recognized.
Then inspect what the
evidence actually covers.

Research experiment · Customer trial ·
Operating record

Who can use it?

Investors

Connect technology to customers and delivery economics.

Companies

Locate suppliers, partners and industrial pathways.

Institutions

Examine research, training, testing and deployment conditions.

Coverage & method

Global country and cluster coverage.

Company, people and institution selections
center on Korea, China and the United States.

Qualitative geographic comparisons.
Contribution-based organizational selections.

Five parts. 46 chapters.

Intelligence

Physical

Capital

Trust

Beyond

Consult it like a guidebook.

Read it like a story.

Check its evidence.



B2AGI almanac · Existing Part V concept artwork

We go where
intelligence
becomes physical.

B2AGI · b2agi.com

Read the comparisons. Follow the sources.